Oriental motor



Bipolar Driver for 2-Phase Stepper Motors Driver for 5-Phase Stepper Motors



RS-485 Communication Type Pulse Input Type





Product Number

CVD	2	B	R	-	Κ	R
1	2	3	4		5	6

1	Series Name	CVD: CVD Series	
2	Matan	2: 1.8°/0.9° Stepper Motor	
	WOLOF	5: 0.72°/0.36° Stepper Motor	
3	Driver Type	B: With Installation Plate	
4	Connector Type	R: Right Angle	
5	Power Supply Input	K: DC Power Supply	
6	Driver Type	R: RS-485 Communication Type	

Product Line

Connector cable sets are available for the motor, power supply, I/O signals, and RS-485 communication (sold separately). The connectors are pre-crimped, making them easy to wire without crimp tools. For details, refer to page 2.

Bipolar Driver for 1.8°/0.9° Stepper Motors

◇Right Angle Type with Installation Plate

Product Name
CVD2BR-KR

• Driver for 0.72°/0.36° Stepper Motors

◇Right Angle Type with Installation Plate

Product Name	
CVD5BR-KR	

Included

Туре	Operating Manual
Common to all types	1 set

CVD2B-KR					

With Installation Plate

 \diamondsuit With Installation Plate

Product Name CVD5B-KR

Specificatio	ons		CE	
Driver P	roduct Name	CVD2B□-KR	CVD5B□-KR	
Driving Method		Microstep Drive, Bipolar, Co	nstant Current Drive Method	
Power Supply Voltage		24 VDC	C±10%	
Rated Current*	А	0.5 to 3.0	0.6 to 3.0	
Direct Inputs		7, Photo-Coupler		
Interface	Direct outputs	2, Photo-Coupler a	and Open-Collector	
	Communication	RS-485 (M	odbus RTU)	
Ambient Temperature		0 to +50°C (Non-freezing)		
Operating Environment	Ambient Humidity	85% or less (N	on-condensing)	
(In operation)	Surrounding Atmosphere	No corrosive The product should not be expo	gas or dust. Ised to water, oil or other liquids	

• For the right angle type with an installation plate, a code **R** (right angle) indicating the connector configuration is entered where the box is located within the driver product name. *The input current value differs depending on the motor used together with the driver.

Refer to page 6.

RS-485 Communication Specifications

Electrical Characteristics	EIA-485 Based Use a shielded twisted pair cable, and keep the total wiring disatance including extension to 10 m or less.	
Communication Mode	Half duplex, asynchronous communication (data: 8 bits, stop bit: 1 bit or 2 bits, parity: none, even or odd)	
Transmission Rate	Select either from 9600 bps, 19200 bps, 38400 bps, 57600 bps, 115200 bps, or 230400 bps.	
Protocol	Modbus RTU Mode	
Connection Units	Up to 31 drivers can be connected to a single host controller.	

Dimensions (Unit: mm)

With Installation Plate

Product Name

CVD2B-KR

CVD5B-KR

Applicable Connectors

Right Angle Type with Installation Plate

Produ	uct Name	Mass [kg]	
CVD2BR-KR CVD5BR-KR		0.005	
		0.065	
Applicable Co	onnectors		
Power Connecto	or (CN1)		
Connector Ho	using: 43645-0200	(Molex)	
Contact:	43030-0001	(Molex)	
Motor Connecto	or (CN2)		
Connector Ho	using: 51103-0500	(Molex)	
Contact:	50351-8100) (Molex)	
RS-485 Commu	inication Connectors	s (CN4, CN5)	
Connector Ho	using: PAP-03V-S (J	.S.T. Mfg Co., Ltd.)	
Contact:	SPHD-001T-P	0.5 or SPHD-002T-P0.5 (J.S.T	. Mfg Co., Ltd.)
I/O Signal Conn	ector (CN6)		
Connector Ho	using: PHDR-12VS (J.S.T. Mfg Co., Ltd.)	
Contact:	SPHD-001T-P	20.5 (J.S.T. Mfg Co., Ltd.)	

Mass [kg]

0.065

Applicable connectors are the same as the right angle type with installation plate.









• Connector cable sets are available for the motor, power supply, I/O signals, and RS-485 communication (sold separately). The connectors pre-crimped, making them easy to wire without crimp tools. For details, refer to page 6.

List of Applicable Motors

Driver for 1.8°/0.9° Stepper Motors

Driver Proc	duct Name	Doted Input Current		
Right Angle Type with Installation Plate	With Installation Plate	Current	[A]	Applicable Motor
		0.5 A/Phase	0.5	PKP213D05
	0.6 A/Phase	0.5	PKP214D06	
		0.85 A/Phase	0.8	PKP24_D08_2
CVD2BR-KR C		1.4 A/Phase	1.3 PKP26 □D14 □2	PKP26_D14_2
	CVD2B-KR	1.5 A/Phase 1.9 PKP22 □ D 1 5□, PKP22 PKP23 □ D 1 5□, PKP262	PKP22_D15_, PKP22_D15_2 PKP23_D15_, PKP262FD15A	
			1.4	PKP24_D15_2, PKP24_MD15_2
		2.3 A/Phase	2.0	PKP23_D23_, PKP24_D23_2
		2.8 A/Phase	3.0	PKP25_D28_A2, PKP26_D28_2 PKP26_MD28_2

Driver for 0.72°/0.36° Stepper Motors

Driver Proc	duct Name	Dotod	Rated Input Current Current [A]		
Right Angle Type with Installation Plate	With Installation Plate	Current		Applicable Motor	
CVD5BR-KR CVD5B-KR		0.35 A/Phase	0.6	PK513, PK52 P	
		0.75 A/Phase	1.4	PK52_H, PK54_	
		1.2 A/Phase	1.7	PKP52	
	CVD3D-KK	1.4 A/Phase	1.8	PK56	
		1.8 A/Phase	2.8	PKP54 N18 2, PKP54 MN	
	2.4 A/Phase	3.0	PKP56_FN24_2, PKP56_FMN		

● A number indicating the length of the motor case is entered where the box □ is located within the names of the applicable motors.

• Either A (single shaft) or B (double shaft) indicating the configuration is specified where the box 📃 is located in the names of the applicable motors.

Motors compatible with the driver are listed to easily distinguish motor and driver combinations.

Combinations with the encoder type and geared type are also available.

For details on the product name, please see the Oriental Motor website.

Note

• Keep the current setting of the driver to less than or equal to the rated current of the motor. If it exceeds the rated current of the motor, the product may be damaged.

Connection and Operation

Names and Functions of Driver Parts

1Signal Monitor Indicators

\bigcirc LED Indicator

Indication	Color	Function	Lighting Condition
	Green	Power Supply lindication	When power is applied
PWR/ALM	Red	Alarm Indication	When a protective function is activated (blinking)
C-DAT/C-ERR	Green	Communication Indication	When communication data is exchanged
	Red	Communication Error Indication	When a communication data error occurs



2 Terminating Resistor Setting Switch

Indication	No.	Function	
SW2	1	Cat the DC 405 communication termination resistor (1200) (Featon: Catting: OFF)	
	2	OFF: no termination resistor, ON: termination resistor (12012) (ractory Setting: OFF)	

3 Motor Setting Switch

Indication	Function
SW1	Sets the applicable motor (Factory Setting: 0)

4USB Communication Connector (CN3)

◇USB Communication Cable Specifications

Specification	USB 2.0 (Full Speed)
Cabla	Length: 3 m or less
Gable	Type: A to mini B

5 RS-485 Communication Connectors (CN4, CN5)

These connectors are used when controlled via RS-485 communication. Connect RS-485 communication cable (sold separately) to either CN4 or CN5 connector. Connect to another driver with the other connector.





RS-485 Communication Cable



6 I/O Signal Connector (CN6)

Indication	Pin No.	Signal Name	Description		
	1	IN-COM	Input Common		
	2	INO	Control Input 0 [FW-POS]	Execute continuous operation in the FWD direction.	
	3	IN1	Control Input 1 [RV-POS]	Execute continuous operation in the RVS direction.	
	4	IN2	Control Input 2 [STOP]	Stop the motor.	
CN6	5	IN3	Control Input 3 [ALM-RST]	Alarm reset.	
	6	IN4	Control Input 4 [HOMES]	Input for mechanical home sensor.	
	7	IN5	Control Input 5 [FW-LS]	Input for a limit sensor in FWD direction.	
	8	IN6	Control Input 6 [RV-LS]	Input for a limit sensor in RVS direction.	
	9	OUT0	Control Output 0 [ALM-B]	Driver alarm status output (normally closed).	
	10	0UT1	Control Output 1 [TIM]	Output when the excitation state of the motor is step "0".	
	11	OUT-COM	Output Common		
	12	N.C.	N.C.		

Connection Diagrams

♦ Connecting to a Current Sink Output Circuit



*The connector pin assignments vary depending on the motor. For details, refer to the connection table on page 5.

\diamondsuit Connecting to a Current Source Output Circuit



* The connector pin assignments vary depending on the motor. For details, refer to the connection table on page 5..

[Note on Wiring]

◇I/O Signal Connection

- Use output signals at 30 VDC or less, 10 mA or less. When the current value exceeds 10 mA, connect an external resistor R0.
- For the I/O signals cable, using a twisted pair cable or a shielded cable is recommended.
- Keep the wiring distance as short as possible (less than 2 m) to limit the effect of noise.
- Provide a distance of 100 mm or more between the control I/O signal lines and power lines (power supply lines, motor lines and other large-current circuits).

◇Power Supply Connection

 Reverse-polarity connection of DC power supply input may cause damage to the driver. When connecting, be sure to check the polarity of the power supply.

\bigcirc Motor Connection

- Up to three cables can be used for the connection between the motor and driver.
- Keep 10 m or less for the wiring distance between the motor and driver.

⇔General

- A separate hand crimp tool is required to crimp the connector and lead wires included with the driver. Connection cables which are available as accessories (sold separately) have already had their lead wires crimped.
- If a specific wiring and layout causes the motor cable or power supply cable to generate a noise problem, shield the cable or use ferrite cores.

- ♦ Connection Table for 2-Phase CVD Driver
- Motor: 0.9°/1.8° PKP/PK Series Bipolar 4 Leads
- Driver: Bipolar Driver for 0.9°/1.8° Stepper Motors



Driver	Model A		Model B		Model C
CN2 Pin No.	Pin No.	Color	Pin No.	Color	Color
1	4	Blue	1	Blue	Blue
2	5	Red	3	Red	Red
3	-	-		-	-
4	2	Green	6	Green	Green
5	1	Black	4	Black	Black

 The Colors in the table represent colors of the lead wires of the connection cables sold separately.

Note

• The motors shown in the model A and model B have different pin assignments. Incorrect connection will prevent the motor from operating correctly.

♦ Connection Table for 5-Phase CVD Driver

Motor: 0.36°/0.72° PKP/PK Series

 \bullet Driver: Bipolar Driver for 0.36°/0.72° 0.36°/0.72° Stepper Motors



Driver	Model A		Model B		Model C
CN2 Pin No.	Pin No.	Color	Pin No.	Color	Color
1	5	Blue	1	Blue	Blue
2	4	Red	2	Red	Red
3	3	Orange	3	Orange	Orange
4	2	Green	4	Green	Green
5	1	Black	5	Black	Black

 The Colors in the table represent colors of the lead wires of the connection cables sold separately.

Power Supply Cable/I/O Signal Cable Set (for RS-485 Communication Type)



Bipolar Driver for 1.8°/0.9° Stepper Motors Unipolar Driver for 1.8°/0.9° Stepper Motors Driver for 0.72°/0.36° Stepper Motors CVD Series Pulse Input Type



These are DC power supply input drivers for stepper motors. The bipolar/unipolar driver for $1.8^{\circ}/0.9^{\circ}$ stepper motor and the driver for $0.72^{\circ}/0.36^{\circ}$ stepper motor are available.

Using the microstep drive function for a low-vibration driver reduces vibration and noise.

Features and Types

 Bipolar/Unipolar Driver for 1.8°/0.9° Stepper Motor Driver for 0.72°/0.36° Stepper Motor

Driver Type		External View	Introduction	Driver Installation Direction
Bipolar Driver for 1.8°/0.9° Stepper Motor Driver for 0.72°/0.36° Stepper Motor	Right Angle Type with Installation Plate	The connector points outward.	 Compact and lightweight driver with a full-time microstep 	 Horizontal direction installation Vertical direction installation
24.5 mm	With Installation Plate	The connector points upward.	 Using the smooth drive function reduces the vibration and noise more than conventional products. The driver is equipped with a protective function that enables you to find driver errors early. 	
 Mass 20 g - 70 g (The value differs according to the driver type.) The driver cannot be shared by both a 1.8°/0.9° stepper motor and 0.72°/0.36° stepper motor. Each must use its respective dedicated driver. 	Without Installation Plate	The connector points upward.	 Running current can be easily set with the digital switch. 	
• Unipolar Driver for 1.8'/0.9' Stepper Motor	50.5 mm 33 mm	The connector points upward.	 Compact and lightweight driver with a microstep Running current can be easily set with the digital switch. 	

Bipolar Driver for 1.8°/0.9° Stepper Motor Driver for 0.72°/0.36° Stepper Motor **CVD** Series Pulse Input Type



1	Driver Type	
2	2: 1.8°/0.9° Stepper Motor	5: 0.72°/0.36° Stepper Motor
3	Rated Current	
4	Driver Identification	
6	Driver Configuration	B: With Installation Plate
9	-	Blank: Without Installation Plate
6	Connector Configuration	R: Right Angle
0	Power Supply Input	K: DC Power Supply

.

Product Line

Bipolar Driver for 1.8°/0.9° Stepper Motor

◇Right Angle Type with Installation Plate

Product Name
CVD205BR-K
CVD206BR-K
CVD215BR-K
CVD223BR-K
CVD223FBR-K
CVD228BR-K
CVD242BR-K
CVD245BR-K

Driver for 0.72°/0.36° Stepper Motor
 Right Angle Type with Installation Plate

♦ 1.3.11
Product Name
CVD503BR-K
CVD507BR-K
CVD512BR-K
CVD514BR-K
CVD518BR-K
CVD524BR-K
CVD528BR-K
CVD538BR-K

Included

Туре	Connector for Driver Connection	Operating manual
Common to All Types	For CN1 (1 Piece) For CN2 (1 Piece) For CN3 (1 Piece)	1 set

With Installation Plate Product Name

Product Name
CVD205B-K
CVD206B-K
CVD215B-K
CVD223B-K
CVD223FB-K
CVD228B-K
CVD242B-K
CVD245B-K

 \diamondsuit With Installation Plate

Product Name
CVD503B-K
CVD507B-K
CVD512B-K
CVD514B-K
CVD518B-K
CVD524B-K
CVD528B-K
CVD538B-K

♦ Without Installation Plate

Product Name
CVD205-K
CVD206-K
CVD215-K
CVD223-K
CVD223F-K
CVD228-K

 \diamondsuit Without Installation Plate

Product Name	
CVD503-K	
CVD507-K	
CVD512-K	
CVD514-K	
CVD518-K	
CVD524-K	

Specifications

Bipolar Driver for 1.8°/0.9° Stepper Motor

	VD242BK CVD245BK						
Drive Method Microstep Drive, Bipolar Constant Current Drive Method							
Motor Drive Current (Factory setting) 0.5 A/Phase 0.6 A/Phase 1.5 A/Phase 2.3 A/Phase 2.8 A/Phase 4.2	4.2 A/Phase 4.5 A/Phase						
Power Supply Voltage 24 VDC±10%							
Input Current A 0.5 0.5 1.3 2.0 3.0	3.6 3.9						
Line driver output by programmable controller: 1 MHz (When the pulse duty is 50%) Maximum Input Pulse Frequency Open-collector output by programmable controller: 250 kHz (When the pulse duty is 50%) Negative logic pulse input							
Operating Ambient Temperature 0 - +50°C (Non-freezing)	0 - +50°C (Non-freezing)						
Environment Ambient Humidity 85% or Less (Non-condensing)	85% or Less (Non-condensing)						
(In operation) Atmosphere No corrosive gases or dust. The product should not be exposed to water, oil or other liquid	No corrosive gases or dust. The product should not be exposed to water, oil or other liquids.						

For the type with installation plate, B (with installation plate) indicating the diver configuration is specified where the box is located in the product name.

For the right angle type with installation plate, an R (right angle) indicating the connector configuration is specified where the box 📃 is located in the product name.

Driver for 0.72°/0.36° Stepper Motor

Produ	uct Name	СVD503	CVD507	CVD512	CVD514	CVD518	CVD524B-K	CVD528B-K	CVD538B-K
Drive Method Microstep Drive, Bipolar Constant Current Drive Method									
Motor Drive ((Factory setti	Current ing)	0.35 A/Phase	0.75 A/Phase	1.2 A/Phase	1.4 A/Phase	1.8 A/Phase	2.4 A/Phase	2.8 A/Phase	3.8 A/Phase
Power Supply Voltage 24 VDC±10%									
Input Current	A	0.6	1.4	1.7	1.8	2.8	3.0	4.8	4.8
Line driver output by programmable controller: 1 MHz (When the pulse duty is Maximum Input Pulse Frequency Open-collector output by programmable controller: 250 kHz (When the pulse Negative logic pulse input			pulse duty is 50%) In the pulse duty is 5	50%)					
Operating Ambient Temperature 0 - +50°C (Non-freezing)									
Environment	Ambient Humidity	85% or Less (Non-condensing)							
(In operation)	Atmosphere		No co	prrosive gases or due	st. The product shou	ld not be exposed to	water, oil or other li	quids.	

• For the type with installation plate, **B** (with installation plate) indicating the diver configuration is specified where the box is located in the product name. For the right angle type with installation plate, an **R** (right angle) indicating the connector configuration is specified where the box is located in the product name.

Dimensions (Unit = mm)

• Right Angle Type with Installation Plate

Product Name	Mass [kg]		
CVD205BR-K			
CVD206BR-K			
CVD215BR-K			
CVD223BR-K			
CVD223FBR-K			
CVD228BR-K	0.06		
CVD503BR-K	0.00		
CVD507BR-K			
CVD512BR-K			
CVD514BR-K			
CVD518BR-K			
CVD524BR-K			
Included			
Connector Housing: 51103-0200 (Molex)			
E1102 (

CONTINUEDIDI	nousing.	31103-0200	(INIDIEN)
		51103-0500	(Molex)
		51103-1200	(Molex)
Contact:		50351-8100	(Molex)

Product Name	Mass [kg]	
CVD242BR-K	0.07	
CVD245BR-K		
CVD528BR-K	- 0.07	
CVD538BR-K	1	
Included		

Connector Housing:	51067-0200	(Molex)
	51067-0500	(Molex)
	51103-1200	(Molex)
Contact:	50217-9101	(Molex)
	50351-8100	(Molex)

•With Installation Plate

Product Name	Mass [kg]		
CVD205B-K			
CVD206B-K			
CVD215B-K			
CVD223B-K			
CVD223FB-K			
CVD228B-K	0.00		
CVD503B-K	0.06		
CVD507B-K			
CVD512B-K			
CVD514B-K			
CVD518B-K			
CVD524B-K			
 Included 			

 Connector Housing:
 51103-0200 (Molex)

 51103-0500 (Molex)
 51103-1200 (Molex)

 50351-8100 (Molex)
 50351-8100 (Molex)

Product Name	Mass [kg]	
CVD242B-K		
CVD245B-K	0.07	
CVD528B-K	0.07	
CVD538B-K	7	

Connector Housing:	51067-0200	(Molex)
	51067-0500	(Molex)
	51103-1200	(Molex)
Contact:	50217-9101	(Molex)
	50351-8100	(Molex)











Without Installation Plate

Product Name	Mass [kg]
CVD205-K	
CVD206-K	1
CVD215-K	1
CVD223-K	
CVD223F-K	1
CVD228-K	0.02
CVD503-K	0.02
CVD507-K	
CVD512-K	
CVD514-K	
CVD518-K	
CVD524-K	
Included	
Connector Housing: 51103-0	1200 (Moley)



Connector Housing: 51103-0200 (Molex) 51103-0500 (Molex) 51103-1200 (Molex) Contact: 50351-8100 (Molex)

List of Applicable Motors

Bipolar Driver for 1.8°/0.9° Stepper Motor

Driver Product Name			Motor Drive	
Right Angle Type with Installation Plate	With Installation Plate	Without Installation Plate	Current (Factory Setting)	Applicable Motor
CVD205BR-K	CVD205B-K	CVD205-K	0.5 A/Phase	PKP213D
CVD206BR-K	CVD206B-K	CVD206-K	0.6 A/Phase	PKP214D
CVD215BR-K	CVD215B-K	CVD215-K	1.5 A/Phase	PKP22_D15, PKP23_D15, PKP24_MD15, PKP262FD
CVD223BR-K	CVD223B-K	CVD223-K	2.3 A/Phase	PKP23_D23
CVD223FBR-K	CVD223FB-K	CVD223F-K	2.3 A/Phase	PKP24_D15_2, PKP24_D23_2
CVD228BR-K	CVD228B-K	CVD228-K	2.8 A/Phase	PKP26_D14_2, PKP26_D28_2, PKP26_MD28
CVD242BR-K	CVD242B-K	-	4.2 A/Phase	PKP26_D42
CVD245BR-K	CVD245B-K	-	4.5 A/Phase	PKP29D

• A number indicating the length of the motor case is entered where the box 🗌 is located within the names of the applicable motors.

• Either A (single shaft) or B (double shaft) indicating the configuration is specified where the box 🔳 is located in the names of the applicable motors.

• The applicable motors are listed such that the available combinations with the driver are distinguishable.

Combinations with the encoder type and geared type are also available.

For details on the product name, please see the Oriental Motor website.

Driver for 0.72°/0.36° Stepper Motor

Driver Product Name			Motor Drive		
Right Angle Type with Installation Plate	With Installation Plate	Without Installation Plate	Current (Factory Setting)	Applicable Motor	
CVD503BR-K	CVD503B-K	CVD503-K	0.35 A/Phase	PK513	
CVD507BR-K	CVD507B-K	CVD507-K	0.75 A/Phase	-	
CVD512BR-K	CVD512B-K	CVD512-K	1.2 A/Phase	PKP52	
CVD514BR-K	CVD514B-K	CVD514-K	1.4 A/Phase	-	
CVD518BR-K	CVD518B-K	CVD518-K	1.8 A/Phase	PKP54	
CVD524BR-K	CVD524B-K	CVD524-K	2.4 A/Phase	PKP56□FN24, PKP56□FMN	
CVD528BR-K	CVD528B-K	-	2.8 A/Phase	PKP56 N28, PK59 H	
CVD538BR-K	CVD538B-K	-	3.8 A/Phase	PKP56□FN38	
· · · · · · · · · · · · · · · · · · ·					

ullet A number indicating the length of the motor case is entered where the box \Box is located within the names of the applicable motors.

• The applicable motors are listed such that the available combinations with the driver are distinguishable.

Combinations with the encoder type and geared type are also available.

For details on the product name, please see the Oriental Motor website.

Connection and Operation (Bipolar Driver for 1.8°/0.9° Stepper Motor and Driver for 0.72°/0.36° Stepper Motor)

Names and Functions of Driver Parts

1 Signal Monitor Indicators

◇LED Indicator

Indication	Color	Function	Lighting Condition
PWR/ALM	Green	Power supply indication	When power is applied
	Red	Alarm indication	When a protective function is activated (blinking)

Blink Count	Function	Operating Condition
2	Overheat Protection	When the temperature of the driver board reaches $85^\circ C$
3	Overvoltage Protection	When the power supply voltage exceeds its permissible value When a large inertial load is stopped suddenly When a large load is hoisted
5	Overcurrent Protection	When an excessive current flows to the motor's output circuit
9	EEPROM error	When data of the driver is damaged
Lighting	CPU error	When the CPU driver malfunctions

2 Function Setting Switch

Indication	No.	Function
1P/2P	1	Switches the pulse input mode between 1-pulse input mode and 2-pulse input mode.
OFF/SD	2	Switches the smooth drive function between enabled and disabled.
R2/R1	3	Use in combination with the step angle setting switch to set the step angle.
STOP	4	Switches the standstill current of motors to 25% or 50%.
OFF/FIL	5	Switches the command filter between enabled and disabled.
-	6	Not used.

Function

3 Step Angle Setting Switch

Indication

STEP	Use ir	combination with the R2/R1 switch to set the step angle.			
Step Angle		R2/R1 Switch: W	hen Set to ON (R1)	R2/R1 Switch: When Set to OFF (R2)	
(STEP) Sca	ale	Resolution (P/R)	Step Angle	Resolution (P/R)	Step Angle
0		500	0.72°	200	1.8°
1		1000	0.36°	400	0.9°
2		1250	0.288°	800	0.45°
3		2000	0.18°	1000	0.36°
4		2500	0.144°	1600	0.225°
5		4000	0.09°	2000	0.18°
6		5000	0.072°	3200	0.1125°
7	7 1000		0.036°	5000	0.072°
8		12500	0.0288°	6400	0.05625°
9		20000	0.018°	10000	0.036°
A		25000	0.0144°	12800	0.028125°
В		40000	0.009°	20000	0.018°
С	C s		0.0072°	25000	0.0144°
D	D 62500		0.00576°	25600	0.0140625°
E		100000	0.0036°	50000	0.0072°
F		125000	0.00288°	51200	0.00703125°

Motor Connector

Power Supply Connector

2

5

3

• Difference in the Motor Responsiveness Depending on the Command Filter (OFF/FIL switch)



 Compared to the standard type, the high-resolution type has 2 times the resolution and 1/2 the step angle.

Example: When the R2/R1 switch is set to ON (R1) and the STEP switch is set to "0"

Resolution of High-Resolution Type: $500 \times 2 = 1000$ Step Angle of High-Resolution Type: $0.72^{\circ}/2 = 0.36^{\circ}$

4 Running Current Setting Switch

Indication	Function		
RUN	Sets the motor running current.		

5 I/O Signal Connector

Indication	Pin No.	I/0	Signal Name	Function
	1	PLS+ (CW+)	Operation command pulse signal	
	2		PLS- (CW-)	(Rotates the motor in the CW direction when in 2-pulse input mode.)
	3		DIR+ (CCW+)	Rotation direction signal
	4	Input	DIR- (CCW-)	(Rotates the motor in the CCW direction when in 2-pulse input mode.)
	5	Input	AW0+	Stop motor expitation
CNO	6 7 8	AW0-		
0103		CS+	Switches the stop angle	
			CS-	
	9	9 ALM- 10 ALM-	ALM+	Outputs the close status for the driver (normally closed)
	10 11 Output		ALM-	
		TIM+	Output when the state of excitation of the motor is the excitation home	
	12	1 [TIM-	position.

Connection Diagram

When the pulse input is the line driver



*This is not available for 1.8° Stepper Motor. Do not connect anything to pin No. 3.

When the pulse input is open collector



[Notes on Wiring]

◇I/O Signal Connection

Input signal

- Use 5 VDC for the input signals
- If voltage exceeding 5 VDC is applied, connect an external resistor R1 so that the current becomes 5~15 mA. (AWO, CS)
- If voltage exceeding 5 VDC is applied to CW input and CCW input when the pulse input is open collector, connect an external resistor R3 so that the current becomes 7~20 mA.
- Use output signals at 30 VDC 10 mA max. When the current value exceeds 10 mA, connect an external resistor R2.
- Use twisted-pair cables of AWG24~22 (0.2~0.3 mm²).
- Note that as the length of the pulse line increases, the max. transmission frequency decreases, and keep the wiring length as short as possible (2 m max.).
- Provide a distance of 100 mm min. between the signal lines and power lines (such as power supply lines and motor lines).

◇Power Supply Connection

- Use a wire of AWG22 (0.3 mm²). Use a wire of AWG20 (0.5 mm²) for CVD242, CVD245, CVD528 and CVD538.
- Incorrect polarities of the DC power-supply input will damage the driver. Make sure that the polarity is correct before turning the power on.

◇Motor Cable Extension

• Use a wire of AWG22 (0.3 mm²) min. Use a wire of AWG20 (0.5 mm²) min. for CVD242, CVD245, CVD528 and CVD538.

General

• A separate hand crimp tool is required to crimp the connector and lead wires included with the driver. Connection cables which are available as accessories (sold separately) have already had their lead wires crimped.

• If a specific wiring and layout causes the motor cable or power supply cable to generate a noise problem, shield the cable or use ferrite cores.



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These products are manufactured at plants certified with the international standards **ISO 9001** (for quality assurance) and **ISO 14001** for systems of environmental management).

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