Oriental motor

αsτεP **AZ Series** EtherNet/IP[™] Compatible Driver

AZ Series drivers now include EtherNet/IP communications for a battery-free, absolute mechanical sensor motor and driver solution.

For use with all Oriental Motor **AZ** Series motors and linear & rotary actuators equipped with the **AZ** Series.



EtherNet/IP Communications

The **AZ** series of motors can be easily added to an existing EtherNet/IP network.





Easily control the **AZ** Series by directly connecting to the EtherNet/IP master device using a standard Ethernet cable. This allows for quick and simple wiring.



EDS File

An EDS file has been prepared to allow EtherNet/IP compatible products to be used more easily. The EDS file can be downloaded from the Oriental Motor website.

System Configuration

AZ Series with EtherNet/IP Compatible Driver

System configuration example of I/O control with EtherNet/IP compatible **AZ** Series driver using EtherNet/IP communications. Motor, driver, and a connection cable set/flexible connection cable set are ordered separately.



Notes

The motor cable and electromagnetic brake cable from the motor cannot be connected directly to the driver. When connecting to the driver, use a connection cable.



Product Line

Power Supply Input	Product Name
Single-Phase 100-120 VAC	AZD-AEP
Single-Phase 200-240 VAC	AZD-CEP

Included

Connector	Operating Manual
CN4 Connector (1 pc.) CN1 Connector (1 pc.) CN7 Connector (1 pc.) Connector Wiring Lever (1 pc.)	1 Copy

Specifications

Communication Specifications

Communications Standards		EtherNet/IP Communication (Conforms with CT16)	
Vendor ID		187: Oriental Motor Company	
Device Type		43: Generic Device	
Transmission Rate		10/100 Mbps (Autonegotiation)	
Communication Mode		Full duplex/Half duplex (Autonegotiation)	
Cable Specifications		Shielded twisted-pair (STP) cable Straight-through/Crossover cable, Category 5e or higher	
Number of Occupied Puter	Output (Scanner \rightarrow Driver)	40 bytes	
Number of occupied bytes	Input (Driver \rightarrow Scanner)	56 bytes	
	Number of Connections	2	
	Connection Type	Exclusive Owner, Input Only	
Implicit Communication	Communication Cycle (RPI)	1 to 3200 ms	
Implicit communication	Connection Type (Scanner \rightarrow Driver)	Point-to-Point	
	Connection Type (Driver \rightarrow Scanner)	Point-to-Point, Multicast	
	Data Trigger	Cyclic	
Explicit Communication	Number of Connections	6	
Explicit Communication	Connection Type	UCMM, Connection	
IP Address Setting Method		IP address setting switch, Parameter, DHCP	
Network Topologies		Star, Linear bus, Ring (Device Level Ring)	

Driver Specifications

Driver Product Name		AZD-AEP	AZD-CEP	
	Input Voltage	Single-Phase 100-120 VAC -15 to +6% 50/60 Hz	Single-Phase 200-240 VAC -15 to +6% 50/60 Hz	
Main Power Supply	Input Current ^{®1} Single-Phase	AZM46: 2.7 A, AZM48: 2.7 A, AZM66: 3.8 A, AZM69: 5.4 A, AZM98: 5.5 A, AZM911: 6.4 A, DGB85: 2.7 A, DGM85: 2.7 A, DGM130: 3.8 A, DGM200: 6.4 A, LM2: 3.8 A, LM4: 3.8 A	AZM46: 1.7 A, AZM48: 1.6 A, AZM66: 2.3 A, AZM69: 3.3 A, AZM98: 3.3 A, AZM911: 3.9 A, DGB85: 1.7 A, DGM85: 1.7 A, DGM130: 2.3 A, DGM200: 3.9 A, LM2: 2.3 A, LM4: 2.3 A	
Control Power Supply Input Voltage Input Current		24 VDC ±5%*2		
		0.25 A (0.5 A)*3		
	Pulse Input	2 inputs, Photocoupler Maximum input pulse frequency Scanner provides line driver output: 1 MHz (50% duty) Scanner provides open collector output: 250 kHz (50% duty)		
Interface	Control Input	6 inputs, Ph	6 inputs, Photocoupler	
Interlace	Pulse Output	2 outputs, Line driver		
	Control Output	6 outputs, Photocoupler/Open collector		
	Power Shut Down Signal Input	2 inputs, Photocoupler		
	Power Shut Down Monitor Output	1 output, Photocoupler/Open collector		
	Field Network	EtherNet/IP		

*1 Varies according to the motor it is combined with.

*2 If an electromagnetic brake motor is used, value is 24 VDC ± 4% when the distance between the motor and driver is extended to 20 m using an Oriental Motor cable.

3 The value inside the () represents the value for an electromagnetic brake motor. For the **AZM46** it is 0.33 A.

General Specifications

Degree of Protection	IP10
Operating Environment	Ambient Temperature: 0 to +55°C (non-freezing)* Humidity: 85% or less (non-condensing) Altitude: Up to 1000 m above sea level Atmosphere: No corrosive gas or dust. The product should not be exposed directly to water, oil or other liquids.
Storage Conditions Shipping Conditions	Ambient Temperature: -25 to +70°C (non-freezing) Humidity: 85% or less (non-condensing) Altitude: Up to 3000 m above sea level Atmosphere: No corrosive gas or dust. The product should not be exposed directly to water, oil or other liquids.
Insulation Resistance	 When a 500 VDC megger is applied to the following locations, resistance is 100 MΩ or higher. Between the protective earth terminal and the main power supply terminal Between the encoder connector and the main power supply terminal Between the input signal terminal and the main power supply terminal
Dielectric Strength	No abnormalities are observed when the specified voltages are applied for 1 minute to the following locations. • Between the protective earth terminal and the main power supply terminal 1.5 kVAC 50/60 Hz • Between the encoder connector and the main power supply terminal 1.8 kVAC 50/60 Hz • Between the input signal terminal and the main power supply terminal 1.8 kVAC 50/60 Hz

* When a heat sink is installed that is equivalent to an aluminum plate with a size of at least 200×200 mm and 2 mm of thickness

Notes

When measuring insulation resistance or testing dielectric strength, please disconnect the motor and driver.

Also, do not perform these tests on the absolute sensor component of the motor.

Dimensions Unit: mm

Product Name	Mass [kg]
AZD-AEP, AZD-CEP	0.68



Included

Main Power Supply/Connector for Regeneration Unit (CN4) Connector: 05JFAT-SAXGDK-H5.0 (J.S.T.) Connector Wiring Lever

24 VDC Power Supply Input/Electromagnetic Brake Connection/Regeneration Unit Thermal Input/Connector for Power Interruption Signal Input/Output (CN1) Connector: DFMC1,5/7-ST-3,5-LR (Phoenix Contact)

I/O Signal Connector (CN7) Connector: DFMC1,5/12-ST-3,5 (Phoenix Contact)

System Configuration

AZ Series with EtherNet/IP Compatible Driver

System configuration example of I/O control with EtherNet/IP compatible **AZ** Series driver using EtherNet/IP communications. Motor, driver, and a connection cable set/flexible connection cable set are ordered separately.



Note

The motor cable and electromagnetic brake cable from the motor cannot be connected directly to the driver. When connecting to a driver, use a connection cable.



1	Driver Type	AZD: AZ Series Driver
2	Power Supply Input	K : 24/48 VDC
3	Network Type	EP: EtherNet/IP



Power Supply Input	Product Name
24/48 VDC	AZD-KEP

Included

Connector	Operating Manual
CN4 Connector (1 pc.) CN1 Connector (1 pc.) CN7 Connector (1 pc.)	1 Сору

Specifications

Communication Specifications

Communication Protocol		EtherNet/IP (Complies with CT16)
Vendor ID		187: Oriental Motor Company
Device Type		43: Generic Device
Baud Rate		10/100 Mbps (Auto-negotiation)
Communication Mode		Full duplex/Half duplex (Auto-negotiation)
Cable Specifications		Shielded twisted-pair wire (STP) cable Straight/Cross, Category 5e or higher
Number of Occupied Puter	Output (Scanner \rightarrow Driver)	40 bytes
Number of Occupied Bytes	Input (Driver \rightarrow Scanner)	56 bytes
	Number of Supported Connections	2
	Connection Type	Exclusive Owner, Listen Only, Input Only
Implicit Communication	Communication Cycle (RPI)	1 to 3200 ms
Implicit communication	Connection Type (Scanner \rightarrow Driver)	Point-to-Point
	Connection Type (Driver \rightarrow Scanner)	Point-to-Point, Multicast
	Data Trigger	Cyclic
Evolicit Communication	Number of Supported Connections	6
Explicit communication	Connection Type	UCMM, Connection
IP Address Setting Method		IP address setting switch, Parameter, DHCP
Supported Topologies		Star, Linear, Ring (Device Level Ring)

Driver Specifications

CE

Driver Product Name A2		AZD-KEP	
Main Power Supply	Input Voltage	24 VDC ±5% 48 VDC ±5%	
	Input Current*1	AZM14: 0.4 A, AZM15: 0.5 A, AZM24: 1.6 A, AZM26: 1.5 A, AZM46: 1.5 A, AZM48: 2.1 A, AZM66: 3.3 A, AZM69: 3.1 A, DGM60: 1.6 A, DGB85: 1.5 A, DGM85: 1.5 A, DGM130: 3.3 A, DR28: 1.3 A, DRSM42: 1.5 A, EH4: 1.6 A	
In In	Input Voltage	24 VDC±5%*2	
Control Power Supply	Input Current	0.15 A (0.4 A)* ³	
	Pulse Input	2 inputs, Photocoupler Maximum input pulse frequency Scanner provides line driver output: 1MHz (50% duty) Scanner provides open collector output: 250kHz (50% duty)	
Interface	Control Input	6 inputs, Photocoupler	
Internace	Pulse Output	2 outputs, Line driver	
	Control Output	6 outputs, Photocoupler/Open collector	
	Power Shut Down Signal Input	2 inputs, Photocoupler	
	Power Shut Down Monitor Output	1 output, Photocoupler/Open collector	
	Field Network	EtherNet/IP	

 $\ensuremath{\ast} 1$ Varies according to the motor it is combined with.

*2 If an electromagnetic brake motor is used, value is 24 VDC ± 4% when the distance between the motor and driver is extended to 20 m using an Oriental Motor cable.

*3 The value inside the () represents the value for a motor with an electromagnetic brake. For the **AZM46** it is 0.23 A.

General Specifications

Degree of Protection	IP10
Operating Environment	Ambient Temperature: 0 to +50°C (non-freezing) Humidity: 85% or less (non-condensing) Altitude: Up to 1000 m above sea level Atmosphere: No corrosive gas or dust. The product should not be exposed directly to water, oil or other liquids.
Storage Conditions Shipping Conditions	Ambient Temperature: -25 to +70°C (non-freezing) Humidity: 85% or less (non-condensing) Altitude: Up to 3000 m above sea level Atmosphere: No corrosive gas or dust. The product should not be exposed directly to water, oil or other liquids.
Insulation Resistance	When a 500 VDC megger is applied to the following locations, resistance is 100 MΩ or higher. · Between the protective earth terminal and the main power supply terminal

Note

When measuring insulation resistance or testing dielectric strength, please disconnect the motor and driver.

Also, do not perform these tests on the absolute sensor component of the motor.

Dimensions Unit: mm



Included Main Power Supply Connector (CN4) Connector: DFMC1,5/3-ST-3,5-LR (Phoenix Contact)

Control Power Supply Connector (CN1) Connector: DFMC0,5/5-ST-2,54 (Phoenix Contact)

I/O Signal Connector (CN7) Connector: DFMC0,5/12-ST-2,54 (Phoenix Contact)

EtherNet/IPTM is a trademark of ODVA (Open DeviceNet Vendor Association).



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Diese Produkte werden in Werken hergestellt, die nach den internationalen Normen ISO 9001 (Qualitätssicherung) und ISO 14001 (Systeme für Umweltmanagement) zertifiziert sind.

Die Angaben können jederzeit ohne Vorankündigung geändert werden. Dieser Katalog wurde im Februar 2024 veröffentlicht.

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