Oriental motor

αstep **AZ Series**EtherCAT Drive Profile Compatible Driver

AZ Series drivers now include EtherCAT communications compatible with CiA 402 drive profile. For use with all Oriental Motor **AZ** Series motors and linear & rotary actuators equipped with the **AZ** Series.



EtherCAT Communications

The **AZ** series of motors can be easily added to an existing EtherCAT network.





Easily control the **AZ** Series by directly connecting to the EtherCAT master device using a standard Ethernet cable. This allows for quick and simple wiring.



ESI File

An ESI file has been prepared to allow EtherCAT compatible products to be used more easily. The ESI file can be downloaded from the Oriental Motor website.

System Configuration

AZ Series with EtherCAT Drive Profile Compatible Driver

Motor, driver, and a connection cable set/flexible connection cable set are ordered separately.



Notes

The motor cable and electromagnetic brake cable from the motor cannot be connected directly to the driver. When connecting to the driver, use a connection cable.



1	Driver Type	AZD: AZ Series Driver
2	Power Supply Input	A: Single-Phase 100-120 VAC C: Single-Phase 200-240 VAC
3	Network Type	ED: EtherCAT Drive Profile

Product Line

Power Supply Input	Product Name
Single-Phase 100-120 VAC	AZD-AED
Single-Phase 200-240 VAC	AZD-CED

Included

Connector	Operating Manual
CN4 Connector (1 pc.) CN1 Connector (1 pc.) CN7 Connector (1 pc.) Connector Wiring Lever (1 pc.)	1 Сору

Specifications

Communications Specifications

Item	Description
Communications Standards	IEC 61158 Type12
Physical Layer/Protocol	100 BASE-TX (IEEE 802.3)
Transmission Rate	100 Mbps
Communication Cycle	Free Run Mode: 1 ms or more SM2 Event Synchronization Mode: 1 ms or more DC Mode: 0.25 ms. 0.5 ms, 1 ms, 2 ms, 3 ms, 4 ms, 5 ms, 6 ms, 7 ms, 8 ms
Communication Port/Connector	RJ45×2 (Shielded) ECAT IN: EtherCAT Input ECAT OUT: EtherCAT Output
Topology	Daisy Chain (Up to 65,535 Nodes)
Process Data	Variable PDO Mapping
Sync Manager	SM0: Mailbox Output SM1: Mailbox Input SM2: Process Data Output SM3: Process Data Input
Mailbox (CoE)	Emergency Message SDO Request SDO Response SDO Information
Synchronization Mode	Free Run Mode (Asynchronous) SM2 Event Synchronization Mode DC Mode (SYNC0 Event Synchronization)
Device Profile	IEC 61800-7 CiA402 Drive Profile

Driver Specifications

Driver Product Name		AZD-AED	AZD-CED	
	Input Voltage	Single-Phase 100-120 VAC -15 to +6% 50/60 Hz	Single-Phase 200-240 VAC -15 to +6% 50/60 Hz	
Main Power Supply	Input Current*1	AZM46: 2.7 A, AZM48: 2.7 A, AZM66: 3.8 A AZM69: 5.4 A, AZM98: 5.5 A, AZM911: 6.4 A DGB85: 2.7 A, DGM85: 2.7 A, DGM130: 3.8 A DGM200: 6.4 A LM2: 3.8 A, LM4: 3.8 A	AZM46: 1.7 A, AZM48: 1.6 A, AZM66: 2.3 A AZM69: 3.3 A, AZM98: 3.3 A, AZM91 1: 3.9 A DGB85: 1.7 A, DGM85: 1.7 A, DGM130: 2.3 A DGM200: 3.9 A LM2: 2.3 A, LM4: 2.3 A	
Control Dowor Supply	Input Voltage	24 VDC ±5%*2		
Control Fower Suppry	Input Current	0.25 A (0.5 A)*3		
	Pulse Input	2 inputs, Photocoupler Maximum input pulse frequency Line Driver: 1 MHz (50% duty) Open Collector: 250 kHz (50% duty)		
Interface	Control Input	6 inputs, Photocoupler		
Interface	Pulse Output	2 outputs, Line driver		
	Control Output	6 outputs, Photocoupler/Open collector		
	Power Shut Down Signal Input	2 inputs, Photocoupler		
	Power Shut Down Monitor Output	1 output, Photocoupler/Open collector		
	Field Network	EtherCAT		

 $\ensuremath{\ast}\ensuremath{1}$ Varies according to the motor it is combined with.

*2 If an electromagnetic brake motor is used, value is 24 VDC \pm 4% when the distance between the motor and driver is extended to 20 m using an Oriental Motor cable.

*3 The value inside the () represents the value for an electromagnetic brake motor. For the **AZM46** it is 0.33 A.

General Specifications

Degree of Protection	1210
Operating Environment	Ambient Temperature: 0 to +55°C (non-freezing)* Humidity: 85% or less (non-condensing) Altitude: Up to 1000 m above sea level Atmosphere: No corrosive gas or dust. The product should not be exposed directly to water, oil or other liquids.
Storage Conditions Shipping Conditions	Ambient Temperature: -25 to +70°C (non-freezing) Humidity: 85% or less (non-condensing) Altitude: Up to 3000 m above sea level Atmosphere: No corrosive gas or dust. The product should not be exposed directly to water, oil or other liquids.
Insulation Resistance	 When a 500 VDC megger is applied to the following locations, resistance is 100 MΩ or higher. Between the protective earth terminal and the main power supply terminal Between the encoder connector and the main power supply terminal Between the input signal terminal and the main power supply terminal
Dielectric Strength	No abnormalities are observed when the specified voltages are applied for 1 minute to the following locations. • Between the protective earth terminal and the main power supply terminal 1.5 kVAC 50/60 Hz • Between the encoder connector and the main power supply terminal 1.8 kVAC 50/60 Hz • Between the input signal terminal and the main power supply terminal 1.8 kVAC 50/60 Hz
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*When a heat sink is installed that is equivalent to an aluminum plate with a size of at least 200×200 mm and 2 mm of thickness

Notes

When measuring insulation resistance or testing dielectric strength, please disconnect the motor and driver.

Also, do not perform these tests on the absolute sensor component of the motor.

Dimensions Unit: mm

Product Name	Mass [kg]
AZD-AED, AZD-CED	0.68



Included

Main Power Supply/Connector for Regeneration Unit (CN4) Connector: 05JFAT-SAXGDK-H5.0 (J.S.T.) Connector Wiring Lever

24 VDC Power Supply Input/Electromagnetic Brake Connection/Regeneration Unit Thermal Input/Connector for Power Interruption Signal Input/Output (CN1) Connector: DFMC1,5/7-ST-3,5-LR (Phoenix Contact)

I/O Signal Connector (CN7) Connector: DFMC1,5/12-ST-3,5 (Phoenix Contact)

System Configuration

AZ Series with EtherCAT Drive Profile Compatible Driver

Motor, driver, and a connection cable set/flexible connection cable set are ordered separately.



Notes

The motor cable and electromagnetic brake cable from the motor cannot be connected directly to the driver. When connecting to a driver, use a connection cable.



Product Line

Power Supply Input	Product Name
24/48 VDC	AZD-KED

Included

Connector	Operating Manual
CN4 Connector (1 pc.) CN1 Connector (1 pc.) CN7 Connector (1 pc.)	1 Сору

Specifications

Communications Specifications

Item	Description
Communications Standards	IEC 61158 Type12
Physical Layer/Protocol	100 BASE-TX (IEEE 802.3)
Transmission Rate	100 Mbps
Communication Cycle	Free Run Mode: 1 ms or more SM2 Event Synchronization Mode: 1 ms or more DC Mode: 0.25 ms. 0.5 ms, 1 ms, 2 ms, 3 ms, 4 ms, 5 ms, 6 ms, 7 ms, 8 ms
Communication Port/Connector	RJ45×2 (Shielded) ECAT IN: EtherCAT Input ECAT 0UT: EtherCAT Output
Тороlоду	Daisy Chain (Up to 65,535 Nodes)
Process Data	Variable PDO Mapping
Sync Manager	SM0: Mailbox Output SM1: Mailbox Input SM2: Process Data Output SM3: Process Data Input
Mailbox (CoE)	Emergency Message SDO Request SDO Response SDO Information
Synchronization Mode	Free Run Mode (Asynchronous) SM2 Event Synchronization Mode DC Mode (SYNC0 Event Synchronization)
Device Profile	IEC 61800-7 CiA402 Drive Profile

Driver Specifications

Driver Product Name AZD-KED 24 VDC ±5% Input Voltage 48 VDC $\pm 5\%$ AZM14: 0.4 A, AZM15: 0.5 A, AZM24: 1.6 A, AZM26: 1.5 A Main Power Supply AZM46: 1.5 A, AZM48: 2.1 A, AZM66: 3.3 A, AZM69: 3.1 A DGM60: 1.6 A, DGB85: 1.5 A, DGM85: 1.5 A Input Current*1 DGM130: 3.3 A, DR28: 1.3 A, DRSM42: 1.5 A EH4: 1.6 A 24 VDC ±5%*2 Input Voltage **Control Power Supply** 0.15 A (0.4 A)*3 Input Current 2 inputs, Photocoupler Maximum input pulse frequency Pulse Input Line Driver: 1 MHz (50% duty) Open Collector: 250 kHz (50% duty) Control Input 6 inputs, Photocoupler Interface Pulse Output 2 outputs, Line driver Control Output 6 outputs, Photocoupler/Open collector Power Shut Down Signal Input 2 inputs, Photocoupler Power Shut Down Monitor Output 1 output, Photocoupler/Open collector Field Network EtherCAT

*1 Varies according to the motor it is combined with.

*2 If an electromagnetic brake motor is used, value is 24 VDC ± 4% when the distance between the motor and driver is extended to 20 m using an Oriental Motor cable.

*****3 The value inside the () represents the value for an electromagnetic brake motor. For the **AZM46** it is 0.23 A.

General Specifications

Degree of Protection	IP10
Operating Environment	Ambient Temperature: 0 to +50°C (non-freezing) Humidity: 85% or less (non-condensing) Altitude: Up to 1000 m above sea level Atmosphere: No corrosive gas or dust. The product should not be exposed directly to water, oil or other liquids.
Storage Conditions Shipping Conditions	Ambient Temperature: -25 to +70°C (non-freezing) Humidity: 85% or less (non-condensing) Altitude: Up to 3000 m above sea level Atmosphere: No corrosive gas or dust. The product should not be exposed directly to water, oil or other liquids.
Insulation Resistance	When a 500 VDC megger is applied to the following locations, resistance is 100 MΩ or higher. • Between the protective earth terminal and the main power supply terminal

Notes

When measuring insulation resistance or testing dielectric strength, please disconnect the motor and driver.

Also, do not perform these tests on the absolute sensor component of the motor.

CE

Dimensions Unit: mm





Included

Main Power Supply Connector (CN4) Connector: DFMC1,5/3-ST-3,5-LR (Phoenix Contact)

Control Power Supply Connector (CN1) Connector: DFMC0,5/5-ST-2,54 (Phoenix Contact)

I/O Signal Connector (CN7) Connector: DFMC0,5/12-ST-2,54 (Phoenix Contact)

EtherCAT® is registered trademark and patented technology, licensed by Beckhoff Automation GmbH, Germany.



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These products are manufactured at plants certified with the international standards **ISO 9001** (for quality assurance) and **ISO 14001** for systems of environmental management).

Specifications are subject to change without notice. This catalogue was published in January 2024.

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